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Stefan Schaffler et al.

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L#	Hits	Search String	Databases
S1	2583	(process near2 control\$3) and (adaptive near2 control\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S2	811	S1 and (measure\$4 or collect\$3) with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S3	495	S1 and (model\$3 with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S4	300	S2 and S3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S5	155	S4 and ((predict\$3 or forecast\$3) with model\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S6	155	S4 and (model\$1 with (accuracy or error\$1))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S7	115	S5 and S6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S8	32	S4 and (model\$3 with regression)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S9	48	S4 and ("mean square" with (error or deviation))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S10	0	S4 and (sort\$3 with data with (error or deviation))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S12	178	S4 and (data with (error or deviation))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S14	57	S4 and ((eliminat\$3 or discard\$3) with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S16	0	S4 and (range with continuous with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
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S21	155	S7 or S8 or S9 or S13 or S15 or S17 or S20	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
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S13	10	S11 and S12	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S15	44	S12 and S14	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S17	6	S4 and (range with continuous)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S22	49	S4 and (continuous with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S23	172	S4 and (data with range)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S24	36	S22 and S23	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S20	12	S18 and S19	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB

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Results of search set L21:S7 or S8 or S9 or S13 or S15 or S17 or S20

Document Kind	Codes	Title
US	20040130442 A1	Wireless and powerless sensor and interrogator
US	20040130276 A1	System and method of applying adaptive control to the control of particle accelerators with val
US	20040129838 A1	Flow control device and method of controlling flow
US	20040117040 A1	System and method of adaptive control of processes with varying dynamics
US	20040111168 A1	Adaptive value generating apparatus, adaptive procedure control program, and adaptive valu
US	20040103108 A1	Method and computer-based system for non-probabilistic hypothesis generation and verificatio
US	20040083993 A1	State space control of solenoids
US	20040083013 A1	Method of operating a plant and a control system for controlling the same
US	20040059441 A1	Klin thermal and combustion control
US	20040031058 A1	Method and apparatus for browsing using alternative linkbases
US	20040015335 A1	Method, system and medium for controlling manufacturing process using adaptive models ba:

Issue Date	Current OR	Abstract
20040708	340/443	
20040708	315/501	
20040708	244/199	
20040617	700/29	
20040610	700/28	
20040527	707/100	
20040506	123/90.11	
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20040122	703/2	

US 20030229900 A1	Method and apparatus for browsing using multiple coordinated device sets	20031211 725/87
US 20030217337 A1	Method for controlling the performance of a target system	20031120 716/1
US 20030195641 A1	State based adaptive feedback feedforward PID controller	20031016 700/42
US 20030093392 A1	System for intelligent control based on soft computing	20030515 706/13
US 20030088322 A1	Kiln thermal and combustion control	20030508 700/53
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US 20030065410 A1	Method and apparatus for controlling a non-linear mill	20030403 700/37
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US 20030049376 A1	Feedback control of sub-atmospheric chemical vapor deposition processes	20030313 427/255.28
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US 20030028265 A1	Kiln/cooler control and upset recovery using a combination of model predictive control and ex	20030206 700/31
US 20030028263 A1	Method and apparatus for adaptive control of marginally stable systems	20030206 700/29
US 20030027424 A1	Feedforward and feedback control for conditioning of chemical mechanical polishing pad	20030206 438/692
US 20030018400 A1	Method and apparatus for creating time-optimal commands for linear systems	20030123 700/29
US 20030018399 A1	Method for optimizing a plant with multiple inputs	20030123 700/28
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US 20030014131 A1	Method for optimizing a plant with multiple inputs	20030116 700/29
US 20020197934 A1	Control of chemical mechanical polishing pad conditioner directional velocity to improve pad li	20021226 451/21
US 20020197745 A1	Feedback control of a chemical mechanical polishing device providing manipulation of remov	20021226 438/5
US 20020186660 A1	Adaptive control of data packet size in networks	20021212 370/248
US 20020156542 A1	Methods, devices and systems for monitoring, controlling and optimizing processes	20021024 700/30
US 20020151992 A1	Media recording device with packet data interface	20021017 700/83
US 20020077537 A1	Ferromagnetic foreign body detection with background canceling	20020620 600/409
US 20020072828 A1	Computer method and apparatus for constraining a non-linear approximator of an empirical pr	20020613 700/269
US 20020053555 A1	Spot welding system and method for sensing welding conditions in real time	20020509 219/110
US 20020044014 A1	Amplifier measurement and modeling processes for use in generating predistortion parameter	20020418 330/2
US 20020016665 A1	System for intelligent control of an engine based on soft computing	20020207 701/106
US 20020016640 A1	Multi-variable matrix process control	20020207 700/29
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US 20010050592 A1	Amplifier measurement and modeling processes for use in generating predistortion parameter	20011213 330/2
US 20010025232 A1	Hybrid linear-neural network process control	20010927 703/13
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US 5991308 A	Lower overhead method for data transmission using ATM and SCDMA over hybrid fiber coax	19991123 370/395.53
US 5933345 A	Method and apparatus for dynamic and steady state modeling over a desired path between tw	19990803 700/44

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US 5867386 A	Morphological pattern recognition based controller system	19990202 700/83
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US 5745652 A	Adaptive resource allocation using neural networks	19980428 706/14
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US 5701400 A	Method and apparatus for applying if-then-else rules to data sets in a relational data base and	19971223 706/45
US 5684650 A	Digital servo control system for use in disk drives	19971104 360/77.06
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US 5638230 A	Digital servo control system for use in disk drives	19970610 360/78.04
US 5602889 A	Digital servo control system for use in disk drives, including sample integrity tester for reducin	19970211 360/78.04
US 5586221 A	Predictive control of rolling mills using neural network gauge estimation	19961217 706/23
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US 5461559 A	Hierarchical control system for molecular beam epitaxy	19951024 700/29
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